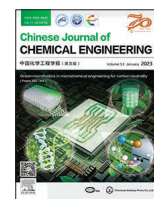




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Full Length Article

Entropy generation analysis from the time-dependent quadratic combined convective flow with multiple diffusions and nonlinear thermal radiation

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ABSTRACT

Diffusions of multiple components have numerous applications such as underground water flow, pollutant movement, stratospheric warming, and food processing. Particularly, liquid hydrogen is used in the cooling process of the aeroplane. Further, liquid nitrogen can find applications in cooling equipment or electronic devices, *i.e.*, high temperature superconducting (HTS) cables. So, herein, we have analysed the entropy generation (EG), nonlinear thermal radiation and unsteady (time-dependent) nature of the flow on quadratic combined convective flow over a permeable slender cylinder with diffusions of liquid hydrogen and nitrogen. The governing equations for flow and heat transfer characteristics are expressed in terms of nonlinear coupled partial differential equations. The solutions of these equations are attempted numerically by employing the quasilinearization technique with the implicit finite difference approximation. It is found that EG is minimum for double diffusion (liquid hydrogen and heat diffusion) than triple diffusion (diffusion of liquid hydrogen, nitrogen and heat). The enhancing values of the radiation parameter R_d and temperature ratio θ_w augment the fluid temperature for steady and unsteady cases as well as the local Nusselt number. Because, the fluid absorbs the heat energy released due to radiation, and in turn releases the heat energy from the cylinder to the surrounding surface.

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1. Introduction

In nature or industries, every flow problem is connected with time *i.e.*, the flow will be of unsteady (time-dependent) nature. For example, biological and geophysical flows, nuclear reactor cooling, materials processing, solar central receivers exposed to wind currents, stall flutter of helicopter blades, flow through turbomachinery blades, *etc.* Here the flow will depend on time. Due to the troublesome approach in solving unsteady flow problems [1–4], many researchers avoid it and concentrate only on steady flow problems. However, Noor *et al.* [1] have worked on unsteady combined convection flow near a porous three-dimensional body in a viscous fluid's stagnation point. Kumari and Nath [2] analysed time-dependent combined convective flow on a semi-infinite vertical plate. Ghalambaz *et al.* [3] have investigated the effect of nano-encapsulated phase change materials (NEPCMs) in a perme-

able medium with time variations. The impact of moving slender cylinder was considered by Roy and Anilkumar [4] in an unsteady combined convection regime.

Triple diffusion occurs when temperature and two species concentration diffusions coexist. Underground water flow, pollutant movement, acid rain effects, stratospheric warming, contaminant transport, food processing and many more are all examples where triple diffusive (multiple diffusion) mixed convection can be useful. In literature, there are limited studies made on the mixed convective triple diffusion flow. Khan *et al.* [5], Ghalambaz *et al.* [6], Khan *et al.* [7], confined their study only to natural convective triply diffusion flow. At the same time, Patil *et al.* [8–10] and Ghalambaz *et al.* [11] extended their work by taking combined convection flow with triple diffusion. Diffusion of liquid nitrogen and hydrogen are considered in this study as they have a lot of applications in heat and mass transfer processes. For instance, liquid hydrogen is used in the cooling process of the aerospace plane [12]. Liquid nitrogen can find applications in cooling equipment or electronic devices, *i.e.*, high temperature superconducting (HTS) cables [13]. Also, in food freezing and to

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cool soft or heat-sensitive materials at room temperatures like plastics, certain metals, tires, and pharmaceuticals [14]. Al-Garni *et al.* [12] concluded that liquid hydrogen outperforms liquid methane as a cooling medium.

Flows past a cylinder are normally regarded as two-dimensional if the body radius is greater than the thickness of the boundary layer. For a slender cylinder, the radius of the cylinder may be of the same order as that of the boundary layer thickness. Therefore, in the case of a slender cylinder, axisymmetric flow is taken into account rather than a two-dimensional flow. Two surface curvatures, the transverse in a plane normal to the axis of symmetry and the longitudinal in the meridian plane, characterise the flow along a thin cylinder [4]. The centrifugal force caused by the longitudinal effect is believed to be relatively negligible in boundary layer analysis. So, in light of the applications, we explored the transverse curvature effect in this study. Chen and Mucoglu [15] discussed the importance of buoyancy in forced convective flow along a vertical cylinder for the first time. Employing the cubic spline interpolation method, Lee *et al.* [16] have investigated the combined convective effect on cylinder and needle. Heckel *et al.* [17] have explored slender cylinder with temperature variations of the surface. Transverse curvature effects on a slender cylinder were analysed by Wang and Klienstreuer [18]. The impact of rotation and time over a slender cylinder was explored in the study of Singh *et al.* [19]. The Nusselt number is more affected by localised cooling/heating than the skin friction coefficient, as evidenced by Kumari and Nath [20]. Aydin and Kaya [21] included MHD in their study over a slender cylinder and revealed that increasing the magnetic term enhances the heat transfer. Takhar *et al.* [22] found that velocity overshoot due to buoyancy forces in their study over a slender cylinder. Patil *et al.* [23,24] have worked on the slender cylinder by considering different effects like viscous dissipation, chemical reaction *etc.* Also, Rehman *et al.* [25] investigated the mixed convection stagnation point flow of Eyring–Powell fluid induced by an inclined cylindrical surface by considering Joule heating and magnetohydrodynamics (MHD).

Combined convective heat and mass transfer is now a common occurrence in various technical and natural systems. According to the second law of thermodynamics, entropy generation (EG) is linked to thermodynamic irreversibility. Entropy production occurs in all thermodynamic systems, and studying EG in a thermodynamical system can aid in improving the system's mechanical efficiency. A viscous fluid containing dissolved solute flows over the surface of a body, irreversible processes such as friction between fluid layers, thermal radiation, chemical reaction *etc.*, occur. EG must be minimised to improve the efficiency of some technical systems, such as fuel cells, air separators, helical coils, microchannel, electro-chemicals, *etc.* The concept of EG was firstly proposed by Bejan [26]. Later, many researchers [5,27–36] have worked on this concept. However, finding the EG of a thermodynamical system to maximise work efficiency remains a significant and unavoidable challenge for researchers. Ahmed *et al.* [27] have focused their work on the effect of thermal stratification on EG. Khan *et al.* [28] explored the impact of EG between two rotating disks when bioconvection nanofluid flows between the disks. Khan *et al.* [29] reviewed the EG on the magnetised rotating hybrid nanoliquid flow amid two parallel plates. Recently, Haq *et al.* [30], Sahoo and Nandkeolyar [31], Khan *et al.* [5], Abbas *et al.* [32], Khan *et al.* [33], Shaw *et al.* [34], Afridi *et al.* [35,36] have worked on the concept of EG.

The difference in temperature between the ambient fluid and the wall does not have to be modest. A substantial difference in these temperatures significantly impacts the heat transfer [37,38] and fluid flow properties that determine the formed material sheet or fibre quality. To overcome this, one has to consider nonlinear (quadratic) temperature density differences in the buoyancy term

of the momentum equation. A very few authors have worked on the nonlinear combined convection impact [39–42].

An examination of the literature reveals that no researchers have investigated the entropy generation effects over a slender cylinder in combination with nonlinear thermal radiation [31,42,43] and nonlinear combined convection. As a result, the current study's goals are centred on the following themes:

- Entropy generation analysis.
- Impact of nonlinear thermal radiation and combined quadratic convection on the profiles and gradients.
- Influence of time-dependent flow nature on the flow characteristics.
- Effect of liquid hydrogen and nitrogen diffusion.
- Impact of viscous dissipation on temperature profile and heat transfer rate.

Further, slender bodies find applications in the coating of wires, fibre sheets, optical fibres, photo electric devices, solar cells *etc.* In fact, thin wires in the shape of a slender cylinder must be cooled during such processes, and the energy and mass transport strengths must be managed to provide better outcomes. Also, liquid hydrogen and liquid nitrogen act as a better cooling agent. In such modelling processes entropy generation occurs, and studying EG in a thermodynamical system can aid in improving the system's mechanical efficiency.

2. Mathematical Formulation

A two-dimensional axisymmetric time-dependent triple diffusive quadratic combined convective flow over a slender cylinder with nonlinear thermal radiation and entropy generation is investigated in this work. The vertical axis of the slender cylindrical wall is used to measure the axial coordinate x , and the radial coordinate r is measured using the cylinder's axis as the starting point. The orifice from which the narrow cylinder emerges is referred to as Origin O . The water is used as the base fluid and liquid hydrogen and nitrogen serving as diffusion components. The radius r_0 of the slender cylinder is equal to the order of the thickness of the boundary layer. In the momentum balance equation, the density variations are accounted for only in the buoyancy term by virtue of the Boussinesq approximation [44,45]. The temperature of the cylinder's wall is T_w , while, T_∞ is the ambient fluid temperature. Further, C_1 , C_2 are the species concentration of liquid hydrogen and nitrogen. Also, C_{1w} , C_{2w} and $C_{1\infty}$, $C_{2\infty}$ are the species concentration at the wall and ambient fluid. Here we assumed that $T_w > T_\infty$, $C_{1w} > C_{1\infty}$, $C_{2w} > C_{2\infty}$. Fig. 1 illustrates the flow geometry of the current problem. The following equations govern the unsteady boundary layer flow around a slender cylinder [4,19,22,23].

$$\frac{\partial(ru)}{\partial x} + \frac{\partial(rv)}{\partial r} = 0 \quad (1)$$

$$\begin{aligned} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial r} = & \frac{\partial U_e}{\partial t} + \frac{v}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u}{\partial r} \right) \\ & + g \left[\beta_1 (T - T_\infty) + \beta_2 (T - T_\infty)^2 + \dots \right] \\ & + g \left[\beta_3 (C_1 - C_{1\infty}) + \beta_4 (C_1 - C_{1\infty})^2 + \dots \right] \\ & + g \left[\beta_5 (C_2 - C_{2\infty}) + \beta_6 (C_2 - C_{2\infty})^2 + \dots \right] \end{aligned} \quad (2)$$

$$\frac{\partial T}{\partial t} + u \frac{\partial T}{\partial x} + v \frac{\partial T}{\partial r} = \frac{\alpha}{r} \frac{\partial}{\partial r} \left(r \frac{\partial T}{\partial r} \right) - \frac{1}{\rho C_p} \frac{\partial q_r}{\partial r} + \frac{v}{C_p} \left(\frac{\partial u}{\partial r} \right)^2 \quad (3)$$

$$\frac{\partial C_1}{\partial t} + u \frac{\partial C_1}{\partial x} + v \frac{\partial C_1}{\partial r} = \frac{D_{s1}}{r} \frac{\partial}{\partial r} \left(r \frac{\partial C_1}{\partial r} \right) \quad (4)$$

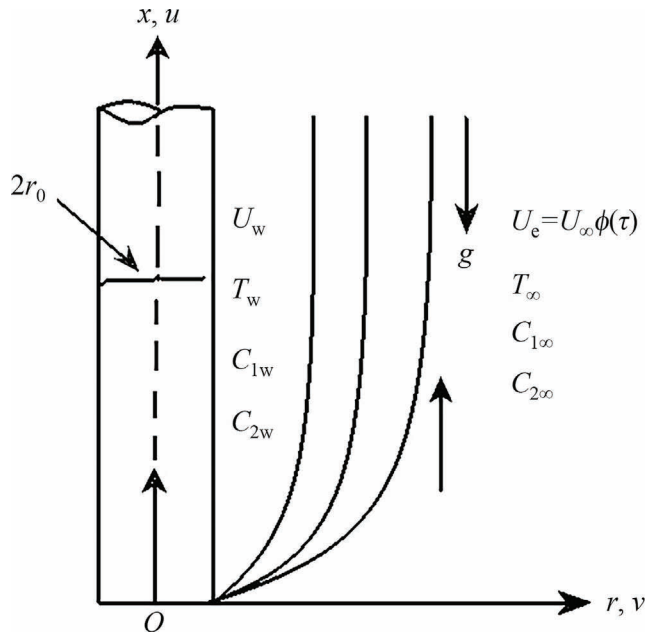


Fig. 1. Flow geometry of the current physical problem.

$$\frac{\partial C_2}{\partial t} + u \frac{\partial C_2}{\partial x} + v \frac{\partial C_2}{\partial r} = \frac{D_{s_2}}{r} \frac{\partial}{\partial r} \left(r \frac{\partial C_2}{\partial r} \right) \quad (5)$$

The initial conditions of the problem are:

$$u(x, r, 0) = u_i(x, r), v(x, r, 0) = v_i(x, r), T(x, r, 0) = T_i(x, r) \\ C_1(x, r, 0) = C_{1i}(x, r), C_2(x, r, 0) = C_{2i}(x, r) \quad (6)$$

The corresponding boundary constraints are:

$$\left. \begin{aligned} \text{At } r = r_0 : u(x, r_0, t) = 0, v(x, r_0, t) = v_w, \\ T(x, r_0, t) = T_w, C_1(x, r_0, t) = C_{1w}, \\ C_2(x, r_0, t) = C_{2w} \\ \text{As } r \rightarrow \infty : u(x, \infty, t) \rightarrow U_e = U_\infty \phi(\tau), \\ T(x, \infty, t) \rightarrow T_\infty, \\ C_1(x, \infty, t) \rightarrow C_{1\infty}, C_2(x, \infty, t) \rightarrow C_{2\infty} \end{aligned} \right\} \quad (7)$$

The non-similar transformations given below are utilised to nondimensionalize the Eqs. (2)–(5) and define the stream function ψ that satisfies the equation of continuity (1):

$$\xi = \left(\frac{4}{r_0} \right) \left(\frac{vx}{U_\infty} \right)^{1/2}, \eta = \left(\frac{U_\infty}{vx} \right)^{1/2} \left[\frac{r^2 - r_0^2}{4r_0} \right], \tau = \frac{vt}{r_0^2}, \\ \frac{r^2}{r_0^2} = (1 + \xi\eta), G = \frac{T - T_\infty}{T_w - T_\infty}, H = \frac{C_1 - C_{1\infty}}{C_{1w} - C_{1\infty}}, \\ S = \frac{C_2 - C_{2\infty}}{C_{2w} - C_{2\infty}}, q_r = - \left(\frac{16\sigma^* T^3}{3k^*} \right) \frac{\partial T}{\partial r}, \\ \psi(x, r, t) = r_0 (vU_\infty x)^{1/2} \phi(\tau) f(\xi, \eta, \tau), F = f_\eta, \text{ where } \phi(\tau) = 1 + \alpha\tau^2, \text{ and } u = \frac{\partial \psi}{\partial y}, v = - \frac{\partial \psi}{\partial x}.$$

Therefore,

$$u = \frac{1}{2} U_e F, \text{ where } U_e = U_\infty \phi(\tau) \text{ and } v = \frac{r_0}{2r} \left(\frac{vU_\infty}{x} \right)^{1/2} \phi(\tau) \{ \eta F - f - \xi f_\xi \}.$$

Thus, the transformed nondimensional equations are:

$$(1 + \xi\eta) F_{\eta\eta} + \left(\xi + \phi f + \xi \phi f_\xi \right) F_\eta + \frac{\xi^2}{4} \left[(2 - F) \phi^{-1} \frac{d\phi}{d\tau} - F_\tau \right] \\ - \xi \phi F F_\xi + 8 Ri \phi^{-1} G (1 + \beta_\tau G) + 8 Ri \phi^{-1} Nc_1 H (1 + \beta_{c_1} H) \\ + 8 Ri \phi^{-1} Nc_2 S (1 + \beta_{c_2} S) = 0 \quad (8)$$

$$(1 + \xi\eta) G_{\eta\eta} + \left(\xi + \frac{\xi}{2P} + \frac{Pr\phi f}{P} + \frac{Pr\xi\phi f_\xi}{P} \right) G_\eta - \frac{Pr\xi^2}{4P} G_\tau \\ - \frac{Pr\xi\phi F G_\xi}{P} + \frac{3R_d(\theta_w - 1)(1 + \xi\eta)Q^2}{P} G_\eta^2 + \frac{PrEc\phi^2(1 + \xi\eta)F_\eta^2}{P} \\ = 0 \quad (9)$$

$$(1 + \xi\eta) H_{\eta\eta} + \left(\xi + Sc_1 \phi f + Sc_1 \xi \phi f_\xi \right) H_\eta - Sc_1 \xi \phi F H_\xi - \frac{Sc_1}{4} \xi^2 H_\tau = 0 \quad (10)$$

$$(1 + \xi\eta) S_{\eta\eta} + \left(\xi + Sc_2 \phi f + Sc_2 \xi \phi f_\xi \right) S_\eta - Sc_2 \xi \phi F S_\xi - \frac{Sc_2}{4} \xi^2 S_\tau = 0 \quad (11)$$

and the pertinent nondimensional boundary constraints are:

$$\left. \begin{aligned} \text{At } \eta = 0 : F(\xi, 0, \tau) = 0, G(\xi, 0, \tau) = 1, \\ H(\xi, 0, \tau) = 1, S(\xi, 0, \tau) = 1 \\ \text{As } \eta \rightarrow \infty : F(\xi, \infty, \tau) \rightarrow 2, G(\xi, \infty, \tau) \rightarrow 0, \\ H(\xi, \infty, \tau) \rightarrow 0, S(\xi, \infty, \tau) \rightarrow 0 \end{aligned} \right\} \quad (12)$$

$$\text{where, } Gr = \frac{g\beta_1(T_w - T_\infty)x^3}{\nu^2}, Re_x = \frac{U_\infty x}{\nu}, Ri = \frac{Gr}{Re_x^2},$$

$$\beta_t = \frac{\beta_2}{\beta_1} (T_w - T_\infty), \beta_{c_1} = \frac{\beta_4}{\beta_3} (C_{1w} - C_{1\infty}), \beta_{c_2} = \frac{\beta_6}{\beta_5} (C_{2w} - C_{2\infty}),$$

$$Nc_1 = \frac{\beta_3(C_{1w} - C_{1\infty})}{\beta_1(T_w - T_\infty)}, Nc_2 = \frac{\beta_5(C_{2w} - C_{2\infty})}{\beta_1(T_w - T_\infty)}, Pr = \frac{\nu}{\alpha},$$

$$R_d = \frac{16\sigma^* T_\infty^3}{3k^*}, \theta_w = \frac{T_w}{T_\infty}, Q = 1 + (\theta_w - 1)G,$$

$$P = (1 + R_d Q^3), Sc_1 = \frac{\nu}{D_{s_1}}, Sc_2 = \frac{\nu}{D_{s_2}}, Ec = \frac{U_\infty^2}{C_p(T_w - T_\infty)}.$$

$$\text{Here, } f(\xi, \eta, \tau) = \int_0^\eta F d\eta + f_w \text{ and } f_w \text{ can be obtained from} \\ v = \frac{r_0}{2r} \left(\frac{vU_\infty}{x} \right)^{1/2} \phi(\tau) \{ \eta F - f - \xi f_\xi \}.$$

Using the boundary condition $v = v_w$ at $\eta = 0$ from Eq. (7),

$$v_w = - \frac{1}{2} \left(\frac{vU_\infty}{x} \right) \phi [f_w + \xi (f_\xi)_w] \text{ after the simplification we get,}$$

$$f_w(\xi, 0, \tau) = A \phi^{-1} \xi, \text{ where } A = \frac{-v_w r_0}{2\nu}.$$

The fluid friction at the surface of the slender cylinder, the energy transfer rate and mass transfer rates at the slender cylinder wall to the ambient fluid are given by the Eqs. (13)–(16), respectively.

$$Re_x^{1/2} C_f = \frac{1}{2} \phi F_\eta(\xi, 0, \tau) \quad (13)$$

$$Nu Re_x^{-1/2} = - \frac{1}{2} (1 + R_d(1 + (\theta_w - 1)G)^3) G_\eta(\xi, 0, \tau) \quad (14)$$

$$Sh_1 Re_x^{-1/2} = - \frac{1}{2} H_\eta(\xi, 0, \tau) \quad (15)$$

$$Sh_2 Re_x^{-1/2} = - \frac{1}{2} S_\eta(\xi, 0, \tau) \quad (16)$$

3. Entropy Generation

The entropy model for the present problem can be written as [5,33–36]:

HTI (heat transfer irreversibility) is the local EG due to heat transfer. Due to the Joule effect and fluid friction, the EG is summed

$$E_{\text{gen}} = \underbrace{\frac{1}{T^2} \left[k \left(\frac{\partial T}{\partial r} \right)^2 + \frac{16\sigma^* T^3}{3k^*} \left(\frac{\partial T}{\partial r} \right)^2 \right]}_{\text{HTI}} + \underbrace{\left[\frac{\mu}{T} \left(\frac{\partial u}{\partial r} \right)^2 \right]}_{\text{FFI}} + \underbrace{\left[\frac{R^* D_{s_1}}{C_{1\infty}} \left(\frac{\partial C_1}{\partial r} \right)^2 + \frac{R^* D_{s_1}}{T_\infty} \left(\frac{\partial C_1}{\partial r} \frac{\partial T}{\partial r} \right) + \frac{R^* D_{s_2}}{C_{2\infty}} \left(\frac{\partial C_2}{\partial r} \right)^2 + \frac{R^* D_{s_2}}{T_\infty} \left(\frac{\partial C_2}{\partial r} \frac{\partial T}{\partial r} \right) + \frac{R^* D_{s_{12}}}{C_{2\infty}} \left(\frac{\partial C_1}{\partial r} \frac{\partial C_2}{\partial r} \right) \right]}_{\text{DI}}$$

up as FFI (fluid friction irreversibility). DI is diffusion irreversibility due to species concentration and temperature. Using the characteristic entropy rate $E_0 = \frac{\Delta T^2 k}{T_\infty^2 x^2}$, the local E_{gen} is nondimensionalized (E_G).

$$E_G = \frac{E_{\text{gen}}}{E_0} = N_1 + N_2 + N_3$$

$$\text{where, } N_1 = \frac{\text{HTI}}{E_0} = \frac{(1 + \xi\eta)}{4(1 + \Omega_T G)^2} Re_x (1 + R_d P) G_\eta^2,$$

$$N_2 = \frac{\text{FFI}}{E_0} = \frac{Br Re_x (1 + \xi\eta)}{16(1 + \Omega_T G) \Omega_T} \phi^2 F_\eta^2,$$

$$N_3 = \frac{\text{DI}}{E_0} = \frac{M_1}{4} \frac{\Omega_{c_1} (1 + \xi\eta) Re_x}{\Omega_T} H_\eta \left(\frac{\Omega_{c_1}}{\Omega_T} H_\eta + G_\eta \right) + \frac{M_2}{4} \times \frac{\Omega_{c_2} (1 + \xi\eta) Re_x}{\Omega_T} S_\eta \left(\frac{\Omega_{c_2}}{\Omega_T} S_\eta + G_\eta \right) + \frac{M_3}{4} \frac{\Omega_{c_2}^2 (1 + \xi\eta) Re_x}{\Omega_T^2} H_\eta S_\eta.$$

$$\text{where, } M_1 = \frac{R^* D_{s_1} C_{1\infty}}{k}, M_2 = \frac{R^* D_{s_2} C_{2\infty}}{k}, M_3 = \frac{R^* D_{s_{12}} C_{1\infty}}{k}, \Omega_T = \frac{\Delta T}{T_\infty},$$

$$\Omega_{c_1} = \frac{\Delta C_1}{C_{1\infty}}, \quad \Omega_{c_2} = \frac{\Delta C_2}{C_{2\infty}}, \quad Pr = \frac{\nu}{\alpha}, \quad Ec = \frac{U_\infty^2}{C_p \Delta T}, \quad Br = Pr Ec,$$

$$Q = [1 + (\theta_w - 1)G] \text{ and } P = (1 + R_d Q^3).$$

And Bejan number is mathematically defined as,

$$\text{Bejan Number, } Be = \frac{\text{HTI}}{E_G} = \frac{N_1}{N_1 + N_2 + N_3} = \frac{\text{Irreversibility due to heat transfer}}{\text{Total local entropy}}$$

which indicates the contribution of entropy generated due to heat transfer relative to the total entropy generated.

4. Numerical Procedure

The method of quasilinearization [9,46,47] is employed to linearize the Eqs. (8)–(11), which is then followed by the implicit finite difference scheme [48–50] to discretize the resulting equations.

$$F_{\eta\eta}^{i+1} + A_1^i F_\eta^{i+1} + A_2^i F_\xi^{i+1} + A_3^i F_\tau^{i+1} + A_4^i F^{i+1} + A_5^i G^{i+1} + A_6^i H^{i+1} + A_7^i S^{i+1} = A_8^i \quad (17)$$

$$G_{\eta\eta}^{i+1} + B_1^i G_\eta^{i+1} + B_2^i G_\xi^{i+1} + B_3^i G_\tau^{i+1} + B_4^i G^{i+1} + B_5^i F^{i+1} + B_6^i F_\eta^{i+1} = B_7^i \quad (18)$$

$$H_{\eta\eta}^{i+1} + C_1^i H_\eta^{i+1} + C_2^i H_\xi^{i+1} + C_3^i H_\tau^{i+1} + C_4^i F^{i+1} = C_5^i \quad (19)$$

$$S_{\eta\eta}^{i+1} + D_1^i S_\eta^{i+1} + D_2^i S_\xi^{i+1} + D_3^i S_\tau^{i+1} + D_4^i F^{i+1} = D_5^i \quad (20)$$

The equivalent boundary conditions are:

$$\left. \begin{aligned} \text{At } \eta = 0 : F^{i+1} = 0, \quad G^{i+1} = 1, \quad H^{i+1} = 1, \quad S^{i+1} = 1 \\ \text{As } \eta = \eta_\infty : F^{i+1} = 2, \quad G^{i+1} = 0, \quad H^{i+1} = 0, \quad S^{i+1} = 0 \end{aligned} \right\} \quad (21)$$

The solution of the so obtained set of linear equations with its coefficient matrix in the block tri-diagonal form is computed by applying Varga's algorithm [51]. The results iteratively converge to the solution with a precision of 10^{-4} . i.e.,

$$\text{Max} \left\{ |(F_\eta)_w^{i+1} - (F_\eta)_w^i|, |(G_\eta)_w^{i+1} - (G_\eta)_w^i|, |(H_\eta)_w^{i+1} - (H_\eta)_w^i|, |(S_\eta)_w^{i+1} - (S_\eta)_w^i| \right\} \leq 10^{-4}.$$

The coefficients of Eqs. (17)–(20) are:

$$\begin{aligned} A_1^i &= \frac{\xi + \phi f + \xi \phi f_\xi}{1 + \xi\eta}, A_2^i = \frac{-\xi \phi F}{1 + \xi\eta}, A_3^i = \frac{-\xi^2}{4(1 + \xi\eta)}, \\ A_4^i &= \frac{-1}{1 + \xi\eta} \left(\frac{\xi^2}{4} \phi^{-1} \phi_\tau + \xi \phi F_\xi \right), A_5^i = \frac{8}{1 + \xi\eta} Ri \phi^{-1} (1 + 2\beta_t G), \\ A_6^i &= \frac{8}{1 + \xi\eta} Ri \phi^{-1} Nc_1 (1 + 2\beta_{c_1} H), \\ A_7^i &= \frac{8}{1 + \xi\eta} Ri \phi^{-1} Nc_2 (1 + 2\beta_{c_2} S), \\ A_8^i &= 2A_3^i \phi^{-1} \phi_\tau + A_2^i F_\xi + \frac{8}{1 + \xi\eta} Ri \phi^{-1} \left(\beta_t G^2 + Nc_1 \beta_{c_1} H^2 + Nc_2 \beta_{c_2} S^2 \right), \\ B_1^i &= \left[\frac{1}{1 + \xi\eta} \left(\frac{\xi}{2} + \frac{\xi}{2P} + \frac{Pr \phi f}{P} + \frac{Pr \phi f_\xi}{P} \right) + \frac{6R_d (\theta_w - 1) Q^2}{P} G_\eta \right], \\ B_2^i &= -\frac{Pr \phi \xi F}{P(1 + \xi\eta)}, B_3^i = -\frac{Pr \xi^2}{4P(1 + \xi\eta)}, \\ B_4^i &= \left[-\left(\frac{\xi}{2} + Pr \phi f + Pr \phi f_\xi \right) - \frac{Pr \xi^2 G_\tau}{4} - Pr \xi \phi F G_\xi \right] \\ &\quad \left(\frac{3R_d (\theta_w - 1) Q^2}{P^2 (1 + \xi\eta)} + 3R_d (\theta_w - 1)^2 Q \left(\frac{2P - 3R_d Q^3}{P^2} \right) \right) \end{aligned}$$

Table 1

Comparison of the present steady-state results ($F_\eta(\xi, 0), G_\eta(\xi, 0)$) with earlier published results

ξ	Ri	Roy and Anilkumar [4]		Singh et al. [19]		Takhar et al. [22]		Present results	
		$F_\eta(\xi, 0)$	$G_\eta(\xi, 0)$	$F_\eta(\xi, 0)$	$G_\eta(\xi, 0)$	$F_\eta(\xi, 0)$	$G_\eta(\xi, 0)$	$F_\eta(\xi, 0)$	$G_\eta(\xi, 0)$
0	0	1.3282	0.5854	1.3281	0.5854	1.3281	0.5854	1.3280	0.5455
0	1	4.9664	0.8220	4.9663	0.8219	4.9665	0.8221	4.9665	0.8220
0	2	7.7122	0.9304	7.7119	0.9302	7.7124	0.9303	7.7121	0.9302
1	0	1.9169	0.8666	1.9167	0.8666	1.9168	0.8668	1.9167	0.8667
1	1	5.2580	1.0621	5.2578	1.0617	5.2580	1.0618	5.2579	1.0618
1	2	7.8871	1.1688	7.8863	1.1685	7.8870	1.1692	7.8868	1.1688

$$\begin{aligned}
& G_\eta^2 + Pr Ec \phi^2 F_\eta^2 \left(\frac{3R_d(\theta_w - 1)Q^2}{P^2} \right) \\
& B_5^i = -\frac{Pr \xi \phi G_\xi}{P(1 + \xi\eta)}, B_6^i = \frac{2Pr Ec \phi^2 F_\eta}{P}, B_7^i = \frac{3R_d(\theta_w - 1)Q^2}{P} \\
& G_\eta^2 + B_2^i G_\xi + B_4^i G + \frac{B_6^i}{2} F_\eta \\
& C_1^i = \frac{1}{1 + \xi\eta} (\xi + Sc_1 \phi f + Sc_1 \phi \xi f_\xi), C_2^i = -\frac{Sc_1 \xi \phi F}{1 + \xi\eta}, \\
& C_3^i = -\frac{Sc_1 \xi^2}{4(1 + \xi\eta)}, \\
& C_4^i = -\frac{Sc_1 \xi \phi H_\xi}{4(1 + \xi\eta)}, C_5^i = C_4^i F, \\
& D_1^i = \frac{1}{1 + \xi\eta} (\xi + Sc_2 \phi f + Sc_2 \phi \xi f_\xi), \\
& D_2^i = -\frac{Sc_2 \xi \phi F}{1 + \xi\eta}, D_3^i = -\frac{Sc_2 \xi^2}{4(1 + \xi\eta)}, \\
& D_4^i = -\frac{Sc_2 \xi \phi S_\xi}{4(1 + \xi\eta)}, D_5^i = D_4^i F.
\end{aligned}$$

In order to validate the authentication of the accuracy of the results of the present analysis, the present results of gradients are compared with the previous research findings of Roy and Anilkumar [4], Singh *et al.* [19] and Takhar *et al.* [22] in Table 1, which shows that the current findings are consistent with the results obtained in [4],[19] and [22].

5. Results and Discussion

The ranges of values of several parameters considered in this study are as follows: $-1 \leq Ri \leq 10$, $-1 \leq A \leq 1$, $0 \leq \tau \leq 1$, $1.5 \leq \theta_w \leq 2.0$, $0 \leq R_d \leq 2$, $-0.5 \leq \alpha \leq 0.5$, $0 \leq \xi \leq 0.5$, $0.5 \leq \Omega_1 \leq 2.0$. Also, some parameter values are kept constant i. e., $Pr = 7$ (water), $Sc_1 = 160$ (liquid hydrogen), $Sc_2 = 240$ (liquid nitrogen) [52].

5.1. Effect of linear and quadratic combined convection parameter

The significance of the impact of linear and quadratic combined convection parameters and time is structured in Figs. 2–5 on the fluid velocity, temperature, local friction coefficient at the surface, and the local energy transfer rate. The profiles are drawn for accelerating flow $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$ and the corresponding gradients are drawn for both accelerating ($\alpha > 0$) and decelerating

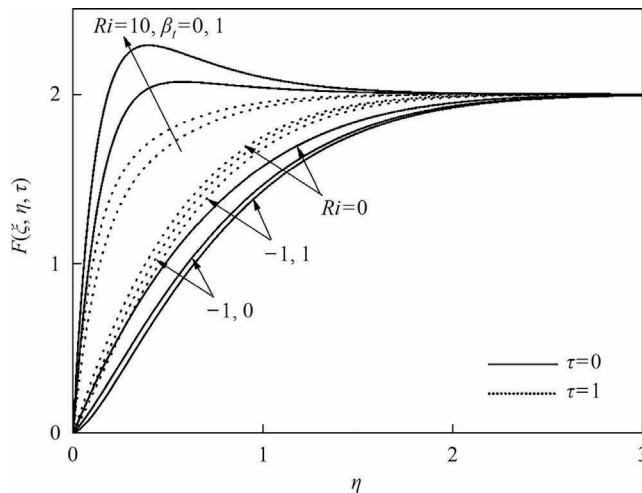


Fig. 2. Variation of velocity $F(\xi, \eta, \tau)$ for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$ for different values of Ri and β_t when $\theta_w = 1.5$, $A = 1$, $\beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = R_d = 0.1$ and $\xi = 0.5$.

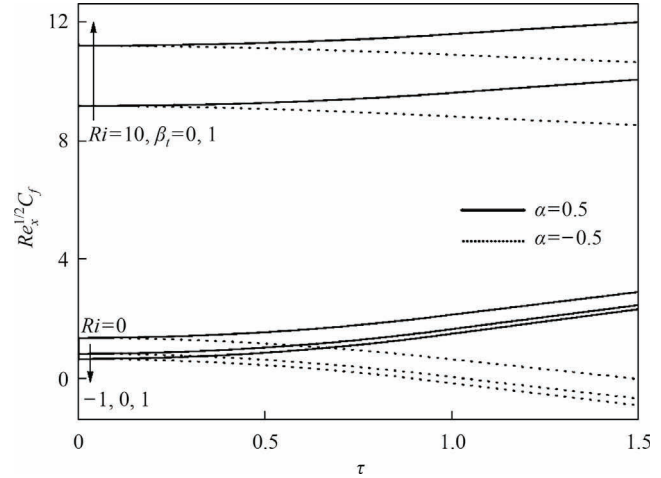


Fig. 3. Variation of local surface friction coefficient for different values of Ri and β_t when $\theta_w = 1.5$, $A = 1$, $\beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = R_d = 0.1$ and $\xi = 0.5$.

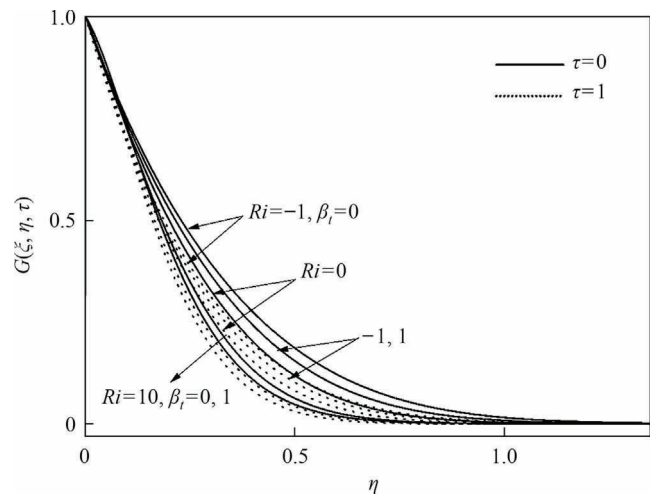


Fig. 4. Variation of temperature $G(\xi, \eta, \tau)$ for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$ for different values of Ri and β_t when $\theta_w = 1.5$, $A = 1$, $\beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = R_d = 0.1$ and $\xi = 0.5$.

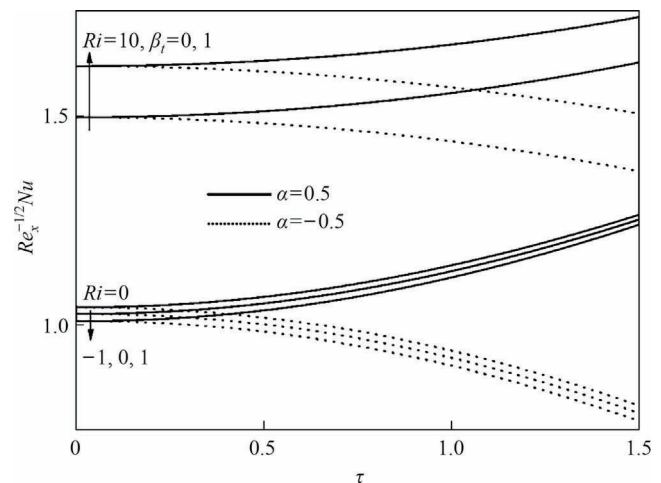


Fig. 5. Variation of local Nusselt number $Re_x^{-1/2} Nu$ for different values of Ri and β_t when $\theta_w = 1.5$, $A = 1$, $\beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = R_d = 0.1$ and $\xi = 0.5$.

($\alpha < 0$) flows. The fluid velocity (F), local friction coefficient at the surface ($Re_x^{1/2} C_f$), and the local energy transfer rate ($Re_x^{-1/2} Nu$) enhance for quadratic combined convection parameter ($\beta_t = 1$) when compared to the linear combined convection parameter ($\beta_t = 0$) while the fluid temperature (G) declines in the case of aiding buoyancy flow ($Ri > 0$) for both time-dependent and independent flows, which is justified by the fact that higher values of β_t causes very intense convection of the fluid particles due to the larger temperature difference. The reverse pattern is found in the case of opposing buoyancy flow ($Ri < 0$). On the other hand, the quadratic combined convection parameter β_t has no effect when $Ri = 0$ as it signifies the forced convection flow. Also, decrement in the fluid velocity and temperature can be seen in Figs. 2 and 4 as time surge when $Ri > 0$.

Further, Ri upsurges the fluid velocity, local friction factor, and thermal efficiency by reducing the temperature of the fluid as it functions as a positive pressure gradient. It is clear from Figs. 3 and 5 that as time surges, the gradients at the surface augment for accelerating flow ($\alpha > 0$) and decline for decelerating flow ($\alpha < 0$). Particularly, the local energy transport strength and friction coefficient at the surface enhance approximately 50% and

87%, respectively, when Ri increments from -1 to 10 at $\tau = 1$, $\beta_t = 1$ and $\alpha = 0.5$.

5.2. Effect of surface mass transfer and streamwise coordinate

Figs. 6 and 7 describe the influence of the surface mass transfer constraint (A) along with the streamwise coordinate ξ and time τ on the temperature profile and the corresponding gradient. The values $\xi \neq 0$ and $\xi = 0$ indicate the non-similarity and similarity solutions, respectively. Since streamwise coordinates behave as a negative pressure gradient, the temperature G of the fluid diminishes in case of suction ($A > 0$) for both $\tau = 0$, $\tau \neq 0$ while energy transport strength enhances. At the same time, the contrary outcomes are observed for injection ($A < 0$). The fluid temperature is more and energy transport strength is less for the permeable surface ($A \neq 0$) when compared with the impermeable surface ($A = 0$) in case of injection ($A < 0$). This is because fluid injection moves the fluid particles from the hotter region near the wall to the colder region away from the surface. Whereas in the case of suction ($A > 0$), quite reverse results are obtained. Specifically, the energy transport strength is approximately 140% more for

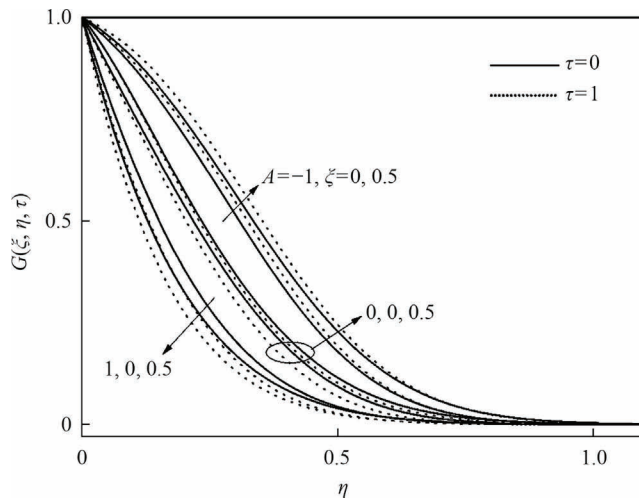


Fig. 6. Variation of temperature $G(\xi, \eta, \tau)$ for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$ for different values of A and ξ when $\theta_w = 1.5$, $Ri = 10$ and $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = R_d = 0.1$.

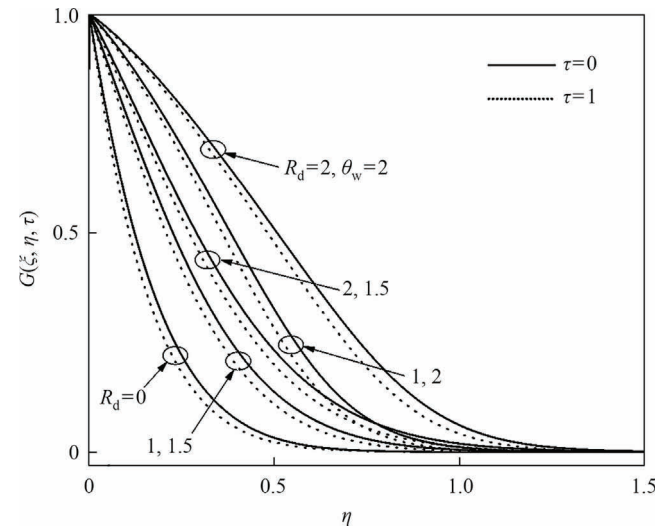


Fig. 8. Variation of temperature $G(\xi, \eta, \tau)$ for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$ for different values of R_d and θ_w when $A = 1$, $Ri = 10$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = 0.1$ and $\xi = 0.5$.

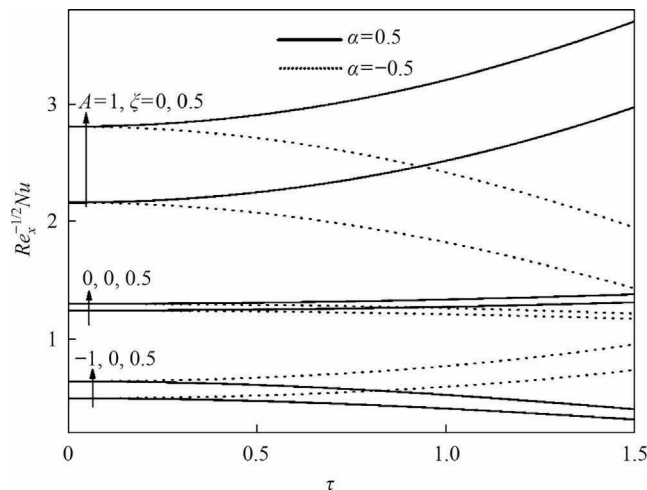


Fig. 7. Variation of $Re_x^{-1/2} Nu$ for different values of A and ξ when $\theta_w = 1.5$, $Ri = 10$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = R_d = 0.1$ and $\xi = 0.5$.

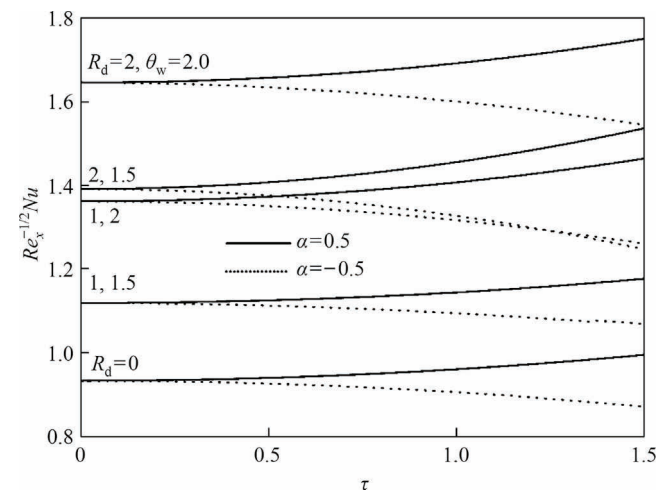


Fig. 9. Variation of $Re_x^{-1/2} Nu$ for different values of R_d and θ_w when $A = 1$, $Ri = 10$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = 0.1$ and $\xi = 0.5$.

5.5. Effect of viscous dissipation

The effect of Eckert number Ec i.e., viscous dissipation along with time τ on temperature profile and local Nusselt number is deliberated in Figs. 12 and 13. The negative values of Ec ($= -0.1$) represent the cooling of the fluid, while positive values ($Ec = 0.1$) represent the heating of the fluid and $Ec = 0$ indicates there is no viscous dissipation. The fluid's temperature enhances for both steady and unsteady cases and the energy transport rate diminishes when the viscous dissipation parameter (Ec) increases, due to the collision between the fluid particles. Particularly, heat transfer rate diminishes by approximately 56% when Ec increases from 0 to 0.1. Also, it is evident from Fig. 13 that, as time upsurges heat transfer rate also enhances for accelerating flow and opposite trend can be seen for decelerating flow.

5.6. Entropy and Bejan number

Figs. 14–18 elucidate the variations of local entropy generation (E_G) and Bejan number (Be) for different Brinkman number Br , temperature ratio parameter Ω_T , time τ and diffusion parameters

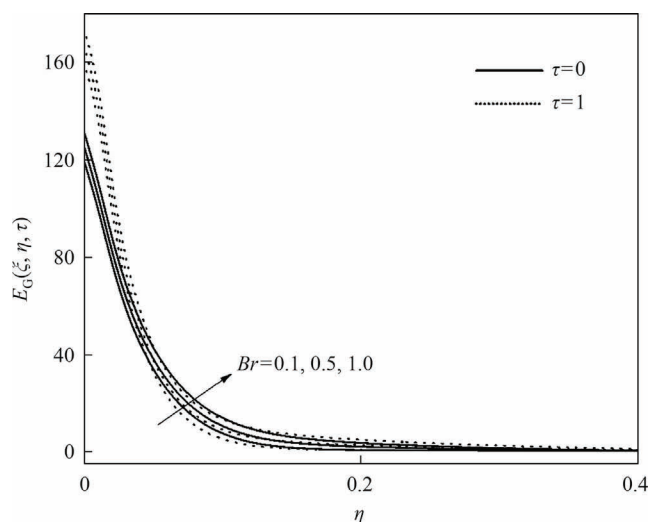


Fig. 14. Effect of Br on entropy generation for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$, when $\theta_w = 1.5$, $Ri = 10$, $\xi = 0.5$, $Re = 10$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = Rd = 0.1$, $M_1 = M_2 = M_3 = 0.5$, and $\Omega_T = \Omega_{c1} = \Omega_{c2} = 0.5$.

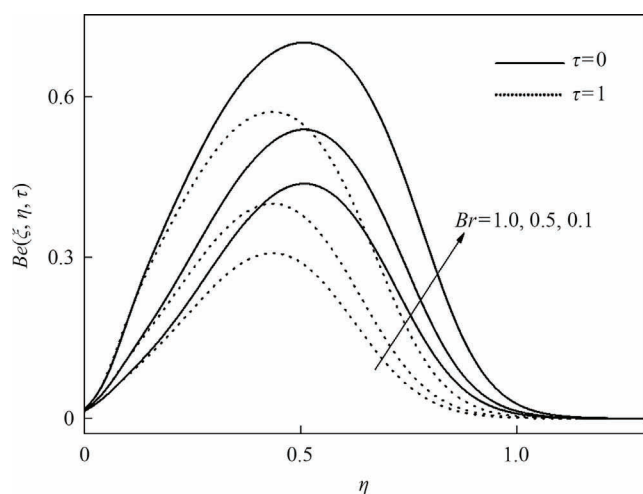


Fig. 15. Effect of Br on Bejan number $Be(\xi, \eta, \tau)$ for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$, when $\theta_w = 1.5$, $Ri = 10$, $\xi = 0.5$, $Re = 10$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = Rd = 0.1$, $M_1 = M_2 = M_3 = 0.5$, and $\Omega_T = \Omega_{c1} = \Omega_{c2} = 0.5$.

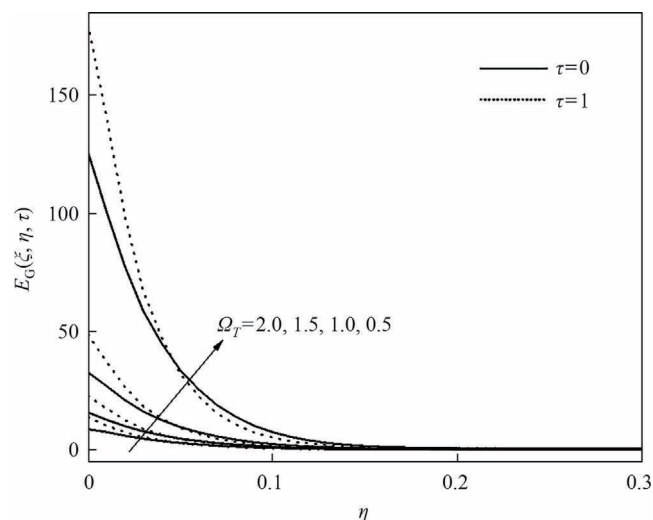


Fig. 16. Effect of Ω_T on entropy generation for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$, when $\theta_w = 1.5$, $Ri = 10$, $\xi = 0.5$, $Re = 10$, $\Omega_{c1} = \Omega_{c2} = 0.5$, $Br = 0.1$, $M_1 = M_2 = M_3 = 0.5$ and $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = Rd = 0.1$.

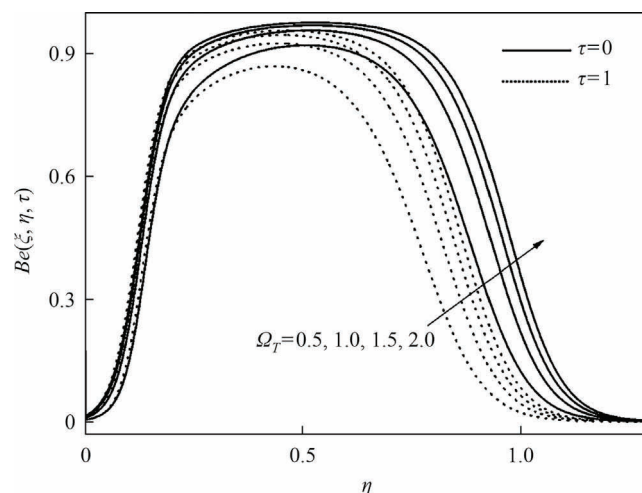


Fig. 17. Effect of Ω_T on Bejan number $Be(\xi, \eta, \tau)$ for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$, when $\theta_w = 1.5$, $Ri = 10$, $\xi = 0.5$, $Re = 10$, $Br = 0.1$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = Rd = 0.1$, $M_1 = M_2 = M_3 = 0.5$, and $\Omega_{c1} = \Omega_{c2} = 0.5$.

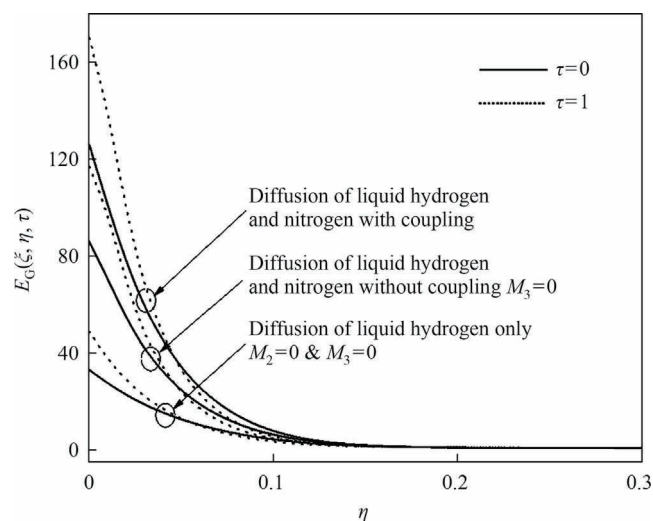


Fig. 18. Effects of M_1 , M_2 and M_3 on entropy generation for $\phi(\tau) = 1 + \alpha\tau^2$, $\alpha = 0.5$, when $\theta_w = 1.5$, $Ri = 10$, $\xi = 0.5$, $Re = 10$, $Br = 0.1$, $\beta_t = \beta_{c1} = \beta_{c2} = Nc_1 = Nc_2 = Rd = 0.1$, and $\Omega_T = \Omega_{c1} = \Omega_{c2} = 0.5$.

M_1 , M_2 and M_3 . It is evident from the figures that EG and Bejan number possess opposite nature as they are inversely proportional. Figs. 14 and 15 demonstrate that the magnitude of E_G enhances and Be reduces for higher values of the Br . This is because, higher magnitude of the Br rises the frictional heating, causing extra energy to the fluid particles, which is the reason behind generating an enormous amount of entropy near the surface. The enhancing values of Ω_T declines the magnitude of E_G , while it surges the magnitude of Be . It is noted that the effect of Ω_T is better noticeable away from the surface.

Furthermore, the higher values of Ω_T reduces the heat transfer, fluid friction and diffusion irreversibility. Thus, the magnitude of E_G is reduced, and Be is enhanced. This is due to the fact that higher values of Ω_T signifies that the temperature of the fluid is more. Also, it is evident from the figures that, as time enhances, the magnitude of Be is reduced and E_G surged. Further, Fig. 18 deliberate the importance of time, diffusing components with and without coupling effects. The entropy generation is minimum for double diffusion (diffusion of liquid hydrogen only) than the triple diffusion (diffusion of liquid hydrogen and nitrogen) with and without coupling the diffusing components. Entropy generation is more when coupling of the diffusion components is considered. The coupling of diffusing components caused by concentration gradients has a significant impact on the entropy generation. Also, it is confirmed that the magnitude of E_G is more pronounced for $\tau = 1$ in all cases.

6. Conclusions

The following inferences are made upon studying the effects of various parameters over different profiles and gradients:

- The enhancing values of Ω_T declines the magnitude of E_G , while it surges the magnitude of Be .
- The entropy generation is minimum for double diffusion (diffusion of liquid hydrogen and heat only) than the triple diffusion (diffusion of liquid hydrogen, nitrogen and heat) with and without coupling the diffusing components.
- The mass transfer strength of liquid nitrogen is about 44% more than that of liquid hydrogen at $\tau = 1, \alpha = 0.5, A = 0.5$. i.e., liquid nitrogen is a better coolant than liquid hydrogen.
- The enhancing values of R_d and θ_w augments the fluid temperature for both $\tau = 0$ and $\tau \neq 0$, concurrently declines the $Re_x^{-1/2}Nu$.
- When comparing the nonlinear thermal radiation with the non-radiation case, the local Nusselt number is lowered by around 58% at $\tau = 1, R_d = 1, \theta_w = 1.5, \alpha = 0.5$.
- The energy transport strength is approximately 140% more for the permeable surface than the impermeable one, in case of suction at $\tau = 1$ when $\xi = 0.5, \alpha = 0.5$.
- The local energy transport strength and friction coefficient at the surface enhance approximately 50% and 87%, respectively, when Ri increments from -1 to 10 at $\tau = 1, \beta_t = 1$ and $\alpha = 0.5$.

Declaration of Competing Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

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Nomenclature

A	suction/injection attribute
Be	Bejan number
Br	Brinkman number
C_f	local friction coefficient at the surface
C_j	species concentration
C_p	specific heat
D_{s_j}	Mass diffusivity
Ec	Eckert number
f	nondimensional stream function
$F=F_\eta$	nondimensional velocity
G	nondimensional temperature
g	acceleration due to gravity
H,S	nondimensional species concentration of liquid hydrogen and nitrogen
K	thermal conductivity
k^*	mean absorption coefficient
M_i	diffusion parameters
Nc_1, Nc_2	buoyancy ratio attributes for liquid hydrogen and nitrogen
Nu	local energy transfer rate
Pr	Prandtl number
q_r	radiative heat flux
R_d	dimensionless nonlinear thermal radiation parameter
R^*	gas constant
r_0	radius of the slender cylinder
Ri	Richardson number
Sc_j	Smidt number
Sh_j	local mass transfer rate
T	temperature of the fluid
T_w	wall temperature
T_∞	ambient fluid temperature
t	time
U_e	mainstream velocity
U_∞	mainstream velocity constant
u, v	components of velocity along x and r directions, respectively
x, r	axial and radial coordinates
α	unsteady parameter
β_1, β_2	coefficients of linear and quadratic thermal expansion
β_3, β_4	liquid hydrogen's linear and quadratic concentration expansion coefficients
β_5, β_6	liquid nitrogen's linear and quadratic concentration expansion coefficients
β_t	quadratic convection parameter for temperature
β_{c_1}	quadratic convection parameter for liquid hydrogen
β_{c_2}	quadratic convection parameter for liquid nitrogen
θ_w	temperature ratio parameter
ξ, η	Transformed variables
ρ	density of the fluid
σ^*	Stefan-Boltzmann constant
τ	nondimensional time
$\phi(\tau)$	unsteady function of τ
ψ	stream function
Ω_{c_1}	ratio of liquid hydrogen concentration
Ω_{c_2}	ratio of liquid nitrogen concentration
Ω_T	ratio of temperature difference

Subscripts

w, ∞	constraints at the surface and away from the surface, respectively
ξ, η	partial derivatives with respect to ξ, η

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